



# Robust and Efficient Computation of Eigenvectors in a Generalized Spectral Method for Constrained Clustering

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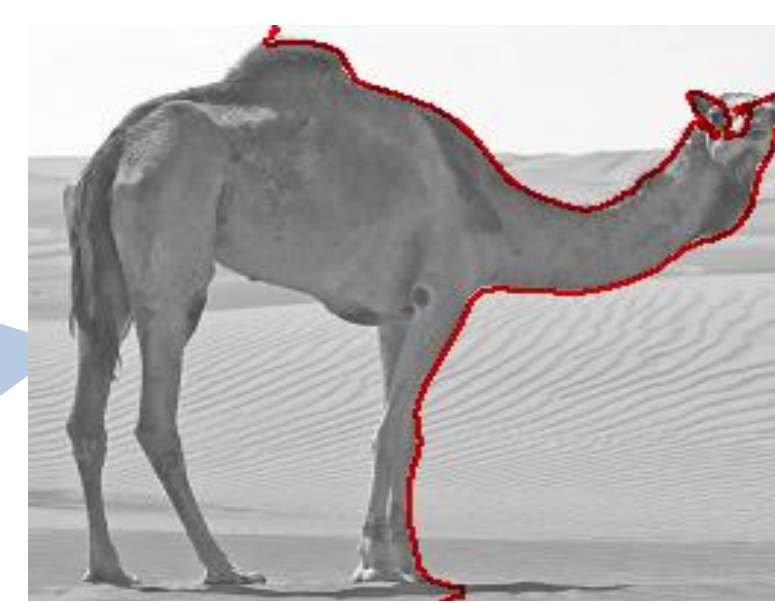
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## Motivation and Objectives

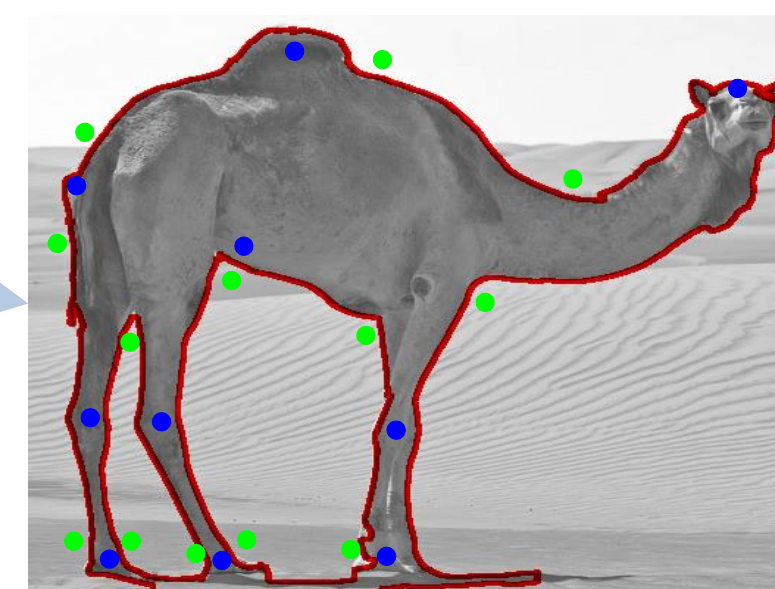
### Image Segmentation



Unconstrained:  
Normalized-Cut (NCut) and  
Spectral-Clustering(SC)



Constrained:  
Must-Link (ML) and  
Cannot-Link (CL) constraints



### Objectives

Mathematically rigorous and computationally effective treatments of FAST-GE model for constrained clustering

## Ncut and FAST-GE

Model	NCut [Shi and Malik, PAMI 2000]	FAST-GE [Cucuringu et al, AISTATS 2016]
Laplacian	L	$L_G, L_H$ with embedded ML and CL constraints
Objective Function	$\frac{cut(A)}{vol(A)} + \frac{cut(\bar{A})}{vol(\bar{A})}$	$\frac{cut_G(A)}{cut_H(A)}$
Rayleigh Quotient Opt.	$\min_x \frac{x^T Lx}{x^T Dx}$ s.t. $x^T D1 = 0$ (1) x is binary (2) L ≥ 0, degree matrix D > 0	$\min_{x^T L_H x > 0} \frac{x^T L_G x}{x^T L_H x}$ (1) x is binary (2) $L_G \geq 0, L_H \geq 0$ (3) $L_G - \lambda L_H$ is singular
Relaxation	$\min_{x \in R^n} \frac{x^T Lx}{x^T Dx}$ s.t. $x^T D1 = 0$	$\inf_{x \in R^n, x^T L_H x > 0} \frac{x^T L_G x}{x^T L_H x}$
Variational Principle	Courant-Fischer	?
Eigenvalue Problem	$Lx = \lambda Dx$	?

## Variational Principles

### Courant-Fischer variational principle

For a symmetric matrix  $L \in R^{n \times n}$ ,  $\lambda_i = \max_{\substack{S \subseteq R^n \\ \dim(S)=n-i+1}} \min_{\substack{x \in S \\ x \neq 0}} \frac{x^T Lx}{x^T x}$

### An extended Courant-Fischer variational principle

For symmetric matrices  $L_G, L_H \in R^{n \times n}$ ,  $L_G, L_H \geq 0$  and  $r = \text{rank}(L_H)$ ,

(1)  $L_G - \lambda L_H$  has r finite eigenvalues  $0 \leq \lambda_1 \leq \dots \leq \lambda_r$

(2)  $\lambda_i = \max_{\substack{S \subseteq R^n \\ \dim(S)=n-i+1}} \min_{\substack{x \in S \\ x^T L_H x > 0}} \frac{x^T L_G x}{x^T L_H x}$

### The extended variational principle implies that

(1)  $\inf_{x \in R^n, x^T L_H x > 0} \frac{x^T L_G x}{x^T L_H x} = \min_{x \in R^n, x^T L_H x > 0} \frac{x^T L_G x}{x^T L_H x} = \lambda_1$  (2) minimizer  $x_1: L_G x_1 = \lambda_1 L_H x_1$

## Eigenvalue Problems

• **The eigenproblem:**  $L_G x = \lambda L_H x$ , where  $L_G, L_H \geq 0$  and  $L_G - \lambda L_H$  is singular.

### Regularization

Let

$$K = -L_H \quad \text{and} \quad M = L_G + \mu L_H + ZSZ^T$$

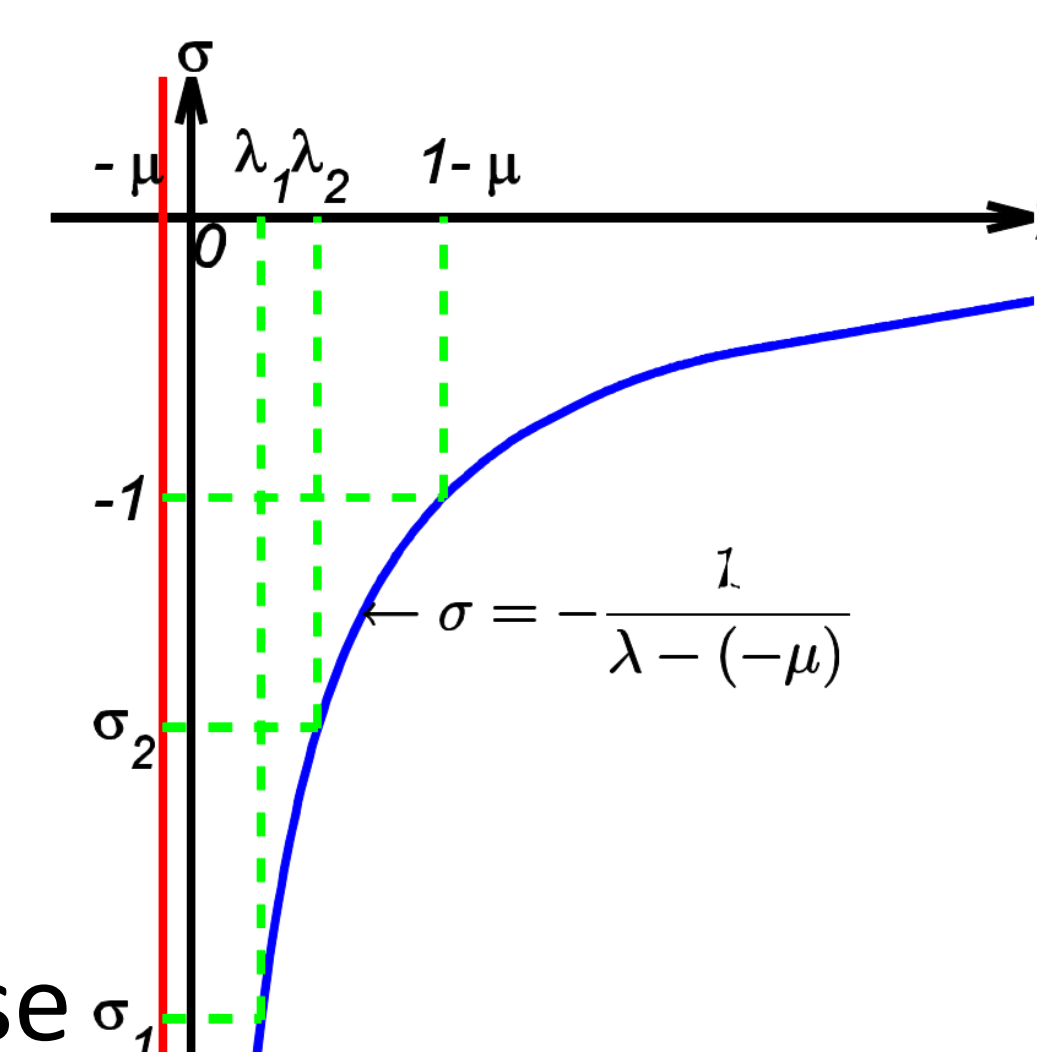
where  $Z = \text{null}(L_G) \cap \text{null}(L_H)$ , S is SPD and  $\mu > 0$  is a scalar. Then:

- (1)  $M > 0$
- (2) The eigenvalues of  $K - \lambda M$  are  $\sigma_1 \leq \dots \leq \sigma_r < \sigma_{r+1} = \dots = \sigma_n = 0$ , where  $\sigma_i = -1 / (\lambda_i + \mu)$  for  $i = 1, 2, \dots, r$

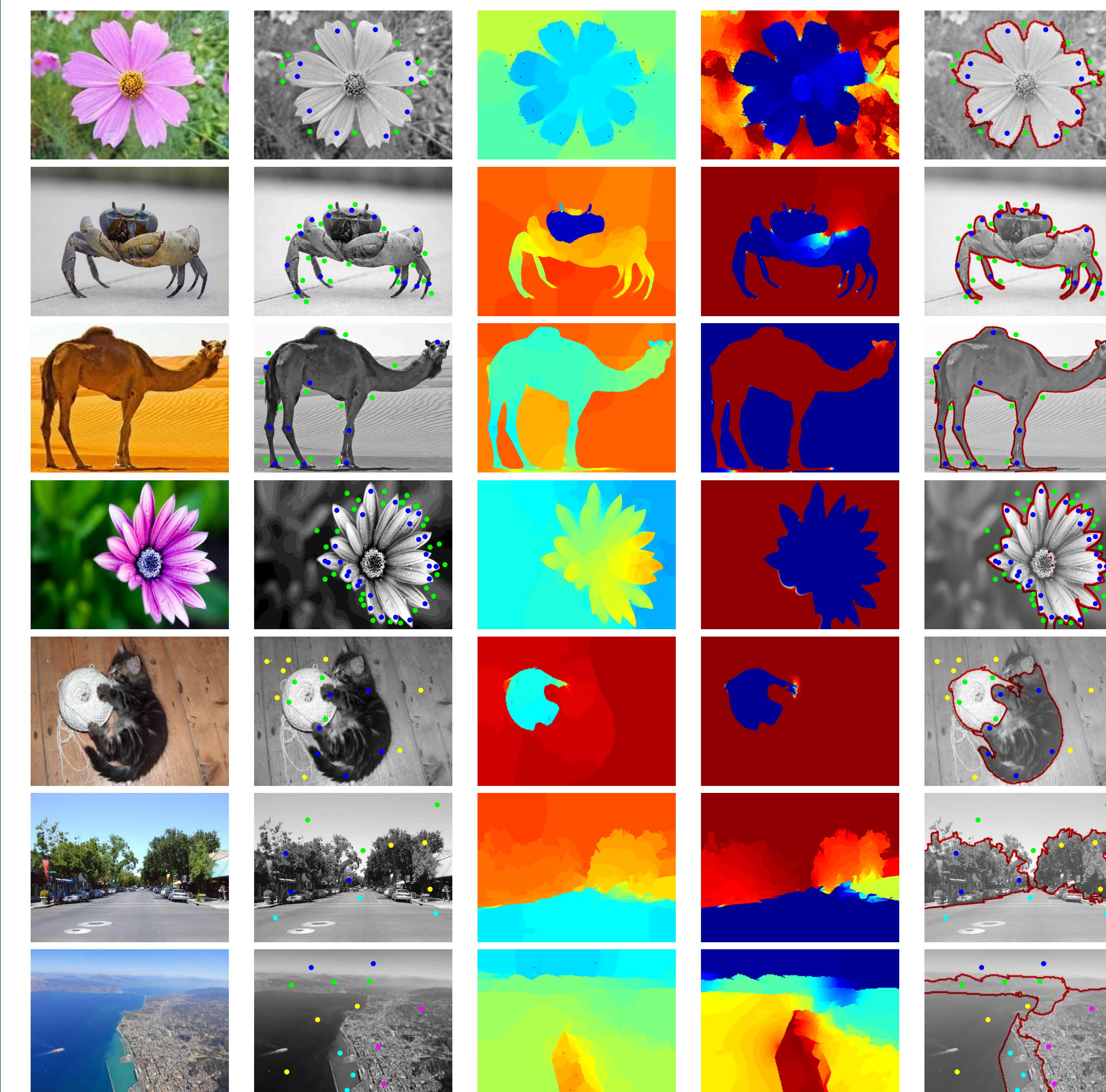
### The generalized symmetric definite eigenvalue problem

$$Kx = \sigma Mx$$

- (1) High-quality solvers (Lanczos and LOBPCG)
- (2) Spectral enhancement without explicit inverse  $\sigma_i$
- (3) "Natural" preconditioner  $T \approx M^{-1}$
- (4) Efficient sparse-plus-low-rank matrix-vector multiplications



## Constrained Image Segmentation



Image, constraints, eigvec, renormalized eigvec, const. seg.

Image	Pixels n	Clusters	Constraints	t_eig(sec)	t_total(sec)
Flower	30,000	2	23	5.88	7.14
Crab	143,000	2	32	55.71	62.14
Camel	249,057	2	23	144.94	159.67
Daisy	1,024,000	2	58	1518.88	1677.51
Cat	50,325	3	18	12.45	15.16
Davis	235,200	4	12	77.9	89.75
Patras	44,589	5	14	11.81	13.72

## Concluding Remarks

1. Provided mathematical foundation and numerical treatment for the FAST-GE model
2. Eigensolver is still the computational bottleneck
3. Future studies: (1) exploiting structures of Laplacians for HPC, (2) other apps such as generalized linear discriminant analysis and multi-surface classification
4. <https://github.com/aistats2017239/fastge2>