#### A Fast Selected Inversion Algorithm for Green's Function Calculation in Many-body Quantum Monte Carlo Simulations

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## Outline

- I. Motivation
- II. Fast Selected Inversion Algorithm
- III. Hybrid Implementation
- IV. QMC Simulation
- V. Concluding Remarks

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#### Hubbard model

► The Hubbard model<sup>1</sup> is defined by the Hamiltonian:

$$\mathcal{H} = \mathcal{H}_K + \mathcal{H}_\mu + \mathcal{H}_V$$

where  $\mathcal{H}_K, \mathcal{H}_\mu$  and  $\mathcal{H}_V$  stands for kinetic, chemical and potential energy, respectively.

Electrons on discrete lattice sites:



# DQMC, QUEST and Green's function

- Determinant Quantum Monte Carlo (DQMC)<sup>2</sup>
  - Simulation on Hubbard Hamiltonian
- QUantum Electron Simulation Toolbox (QUEST) <sup>3</sup>
  - A state-of-art implementation of DQMC simulations
- Green's function calculation
  - computational kernel of QUEST
  - inverses of thousands of Hubbard matrices
  - $\blacktriangleright$  matrix dimension  $NL \times NL$
  - $\blacktriangleright ~NL \approx 10^3 \cdot 10^2$

<sup>3</sup>http://quest.ucdavis.edu/

<sup>&</sup>lt;sup>2</sup>R. Blankenbecler, D. Salapino, R. Sugar, 1981.

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 Green's function can be defined by the inverse of the following block p-cyclic matrix in the normal form

$$A = \begin{bmatrix} A_{11} & & & A_{1L} \\ A_{21} & A_{22} & & & \\ & \ddots & \ddots & & \\ & & & A_{L,L-1} & A_{LL} \end{bmatrix},$$

where each block is  $N \times N$  square and the diagonal block matrices  $A_{ii}$  for  $1 \le i \le L$  are nonsingular.

• Let 
$$D = diag(A_{11}, A_{22}, \dots, A_{LL})$$
, then

$$M = D^{-1}A = \begin{bmatrix} I & & B_1 \\ -B_2 & I & & \\ & \ddots & \ddots & \\ & & -B_L & I \end{bmatrix},$$

where  $B_1 = A_{11}^{-1}A_{1L}$  and  $B_i = -A_{ii}^{-1}A_{i,i-1}$  for  $2 \le i \le L$ .

• A block LU factorization of M is given by M = LU where

$$L = \begin{bmatrix} I & & & \\ -B_2 & I & & \\ & -B_3 & I & \\ & & \ddots & \ddots & \\ & & & -B_L & I \end{bmatrix}$$

and

$$U = \begin{bmatrix} I & & B_1 \\ I & & B_2B_1 \\ & \ddots & & \vdots \\ & & I & B_{L-1}B_{L-2}\cdots B_1 \\ & & & I + B_LB_{L-1}\cdots B_1 \end{bmatrix}$$

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• The inverses of L and U are given by

$$L^{-1} = \begin{bmatrix} I & & & \\ B_2 & I & & \\ B_3 B_2 & B_3 & I & \\ \vdots & \vdots & \ddots & \ddots \\ B_L \cdots B_2 & B_L \cdots B_3 & \cdots & B_L & I \end{bmatrix}$$

and

$$U^{-1} = \begin{bmatrix} I & & -B_1F \\ I & & -B_2B_1F \\ & \ddots & & \vdots \\ & & I & -B_{L-1}B_{L-2}\cdots B_1F \\ & & & F \end{bmatrix},$$

where  $F = (I + B_L B_{L-1} \cdots B_2 B_1)^{-1}$ .

 $\blacktriangleright$  Consequently, the inverse of M, denoted by G, is then given by

$$G = M^{-1} = U^{-1}L^{-1} = (G_{k\ell})$$

where for  $1 \leq k, \ell \leq L$ ,

$$G_{k\ell} = W_{kk}^{-1} Z_{k\ell},$$

and

$$W_{kk} = \begin{cases} I + B_k B_{k-1} \cdots B_1 B_L \cdots B_{k+1}, & 1 \le k \le L-1 \\ I + B_L B_{L-1} \cdots B_1, & k = L \end{cases}$$

and

$$Z_{k\ell} = \begin{cases} -B_k B_{k-1} \cdots B_1 B_L B_{L-1} \cdots B_{\ell+1}, & k < \ell < L \\ -B_k B_{k-1} \cdots B_1, & k < \ell = L \\ I, & k = \ell \\ B_k B_{k-1} \cdots B_{\ell+1}, & k > \ell \end{cases}$$

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Relations between adjacent blocks of Green's function



#### Selected inversion

Commonly selected patterns:



- Related works
  - Estimating trace of the matrix inverse [Stathopoulos, et al., 2013]
  - Subset of selected elements of the inverse matrix [L. Lin, et al., 2011]

## **FSI** overview

- Fast selected inversion (FSI) algorithm:
  - 1. Clustering
    - block cyclic reduction (BCR)
  - 2. Inversion
    - block structured orthogonal factorization and inversion (BSOFI)<sup>4</sup>
  - 3. Wrapping
    - $\blacktriangleright$  seeds + adjacency relations  $\rightarrow$  selected inversion



<sup>4</sup>S. Gogolenko, Z. Bai, R. Scalettar, 2014

## Clustering

•  $\widehat{M} = \mathsf{CLS}(M, c, q)$  is for a factor-of-c BCR of M, i.e.,

$$\widehat{M} = \begin{bmatrix} I & & & & & \\ -\widehat{B}_2 & I & & & \\ & -\widehat{B}_3 & I & & \\ & & \ddots & \ddots & \\ & & & -\widehat{B}_b & I \end{bmatrix},$$

where 
$$\widehat{B}_i = B_j B_{j-1} \cdots B_{j-c+1}$$
 and  $j = ci - q$ .

- Computational cost:  $2b(c-1)N^3$
- Embarrassingly parallel



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# Inversion

• 
$$\widehat{G} = \widehat{M}^{-1} = (\widehat{G}_{ij})$$
 by BSOFI

- Block structured orthogonal factorization and inversion
- $\blacktriangleright\,$  QR decomposition only on the  $2N\times N$  dense blocks
- Numerically stable
- Lower computational complexity  $(7b^2N^3)$  than the inversion by full QR  $(2b^3N^3)$ .



## Wrapping

A crucial observation:

$$\widehat{G}_{i,j} = G_{ci-q,cj-q} \equiv G_{k\ell} \quad \text{for } 1 \le i,j \le b.$$

- $G_{k\ell}$  + adjacency relations  $\rightarrow S$ 
  - Selected columns:  $G_{k\ell} \rightsquigarrow G_{k+1,\ell} \rightsquigarrow G_{k+2,\ell} \rightsquigarrow \ldots$
  - Selected rows:  $G_{k\ell} \rightsquigarrow G_{k,\ell+1} \rightsquigarrow G_{k,\ell+2} \rightsquigarrow \ldots$
- Computational cost:  $3b(L-b)N^3$
- Embarassingly parallel



# Advantages of FSI

Computational cost (b selected block columns)

	complexity	FSI reduced factor
LU	$O(L^3N^3)$	$L^2/b$
Explicit form	$O(bL^2N^3)$	L
BSOFI	$O(L^2N^3)$	L/b
FSI	$O(bLN^3)$	1

- Memory requirement
  - ► Full inversion methods like LU or BSOFI are not feasible.
- Stability
  - ▶ FSI is more numerically stable than explicit form.
- Parallelism
  - ► FSI is embarrassingly parallel.

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#### Architecture

- Hierarchical architecture
  - Multiple nodes
  - Multiple sockets
  - Multiple cores
- NERSC's supercomputer Edison
  - ▶ 5576 compute nodes
  - 2 sockets per node
  - 12 cores per socket (133824 cores in total)
- A cray X-30 dual-socket node



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#### Two levels of parallelism



OpenMP level

- Clustering: compute  $\widehat{B}_i$  for  $1 \le i \le b$  in parallel by OpenMP;
- Inversion: run BSOFI by using multi-threaded MKL routine;
- ▶ Wrapping: computes the neighbors of G<sub>kℓ</sub> for 1 ≤ k, ℓ ≤ b in parallel by OpenMP.
- MPI level
  - Generate and distribute all the Hubbard matrices by MPI processes;
  - Each MPI process runs the FSI with OpenMP.

#### Parallel application of FSI

► A pictorial illustration:



# **FSI** performance

- FSI with OpenMP on a single 12-core Intel "Ivy Bridge" processor;
- (N, L, c) = (576, 100, 10);
- Selected inversion of b = L/c = 10 block columns;



80% improvement.

## **FSI** performance

- FSI with OpenMP on a single 12-core Intel "Ivy Bridge" processor;
- (L, c) = (100, 10);
- Selected inversion of b = L/c = 10 block columns;



Close to MKL BLAS-3 DGEMM.

## **FSI** performance

- FSI with OpenMP/MPI on 100 dual-socket Edison compute nodes (2400 cores):
- (L, c) = (100, 10);



- Pure MPI execution is restricted due to the memory capacity;
- Hybrid implementation achieves best performance for large scale matrices.

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## **DQMC** overview

#### Algorithm 1 DQMC simulation

initialize HS configuration  $h_0 = (h_{\ell i}) = (\pm 1)$ % Warmup stage for i=1,...,w do DQMC sweep end for % Measurement stage for i=1,...,m do DQMC sweep compute Green's function and physical measurements end for

## **DQMC** sweep

Algorithm 2 DQMC sweep for  $\ell = 1, 2, ..., L$  do for i = 1, 2, ..., N do (1) Propose a new configuration:  $h'_{\ell i} = -h_{\ell i}$ ; (2) Compute the Metropolis ratio:  $r_{\ell i} = \frac{\det[M_{+}(h')] \det[M_{-}(h')]}{\det[M_{+}(h)] \det[M_{-}(h)]};$ (3) Apply Metropolis acceptance-rejection: randomize  $r \sim uniform[0, 1]$ , if  $r \leq \min\{1, r_{\ell i}\}$  then h = h'. end if end for end for

# FSI in DQMC

- Runtime profile on a single Hubbard matrix with (L, N, c) = (100, 400, 10);
- ► All the diagonal blocks, *b* block rows and *b* block columns of each *G* are computed.



# **FSI in DQMC**

- Runtime of a full DQMC simulation on an "Ivy Bridge" processor of Edision;
- (w,m) = (100,200);
- (L, N, c) = (100, 400, 10);



- FSI with MKL only gains a factor of 1.3 speedup;
- ► FSI with OpenMP gains a factor of 6.9 speedup → ( = ) ( = )

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## **Concluding Remarks**

Conclusion:

- Parallel FSI enhances QMC capabilities.
- Solutions of problems that require larger number of electrons will be allowed.
- More complicated types of interactions can be studied.

Future work:

- Extension of FSI to other types of structured matrices.
- ► GPU implementation of FSI.
- Hybrid massive parallelization of the full DQMC simulation.

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